



THEORY (20 HOURS)

1.- BASIC INTRODUCTION TO VEHICLE TELEMATICS

1.1.- IN-VEHICLE NETWORKS - 30 MINS

- ¹ Electronic Control Units (ECUs). Networking advantages.

1.2.- PROTOCOLS (OVERVIEW) – 60 MINS

- Procols classification. Short explanation about CAN, LIN, MOST and discrete line.

1.2.1.- CAN

1.2.2.- LIN

1.2.3.- D2B

1.2.4.- MOST

1.2.5.- FLEXRAY

1.3.- CAR ARCHITECTURES – 40 MINS

1.3.1.- 220: S-CLASS

- Vehicle topology and bench

1.3.2.- 211: E-CLASS

- Vehicle topology and bench

1.3.3.- 203: C-CLASS

- Vehicle topology and bench

1.4.- VEHICLE DIAGNOSTICS – 30 MINS

- On Board Diagnostics(OBD), diagnostics tools and communication protocols

2.- CAN: CONTROLLER AREA NETWORK

2.1.- INTRODUCTION – 50 MINS

2.1.1.- NETWORKING TOPOLOGY OPTIONS. – 10 MINS

- Advantages of the bus communication.

2.1.2.- BUS SELECTION. – 10 MINS

- Looking for low cost, high speed and reliability.
- Graphic with different protocols according to speed and cost.

2.1.3.- CAN BASICS – 30 MINS

- Physical layer.
- Bitrate according to cable length.
- Highspeed and Lowspeed CAN.

2.2.- CAN PROTOCOL – 90 MINS

2.2.1.- CAN FRAMES - 20 MINS

- Frames: Standard, extended, Error, Remote and Overload
- Coding for CAN bus: NRZ

2.2.2.- FRAME FORMAT – 30 MINS

- Standard frame
 - Frame data: Fields and length.
 - Example of one frame
- Extended Frame
 - Frame data: Fields and length.
 - Example of one frame
- Remote Frame

2.2.3.- CODING AND BITSTUFFING – 10 MINS

- Explanation about bit stuffing

2.2.4.- ERROR HANDLING – 30 MINS

- Frame transmission and collision detection in CSMA/CD.

¹ • = content or idea to be explained to students.



- Error frame
- Overload frame
- 2.3.- DATA EXCHANGE – 60 MINS
 - 2.3.1.- MESSAGES AND SIGNALS – 30 MINS
 - How a signal fits into a message. How information fits into a signal. Example.
 - 2.3.2.- K-MATRIX – 30 MINS
 - 211 K-matrix explanation: type of signals, ECUs...
 - Different K-matrix for every CAN (CAN B, CAN D, CAN C)
 - Every vehicle model may have different K-Matrix which may change also from release to release.
- 2.4.- NETWORK MANAGEMENT – 20 MINS
 - Ring between CAN nodes, addresses and network management messages and signals.
- 2.5.- TRANSPORT PROTOCOL – 30 MINS
 - Description and examples (W_REG, AW_REG, DEL...).
 - Transport protocol disassembler
- 2.6.- CAN BEYOND THE AUTOMOTIVE INDUSTRY – 40 MINS
 - CAN protocols: CANopen, CANaerospace
 - Examples: spacecraft, locomotive.
- 3.- CANOE: CAN OPEN ENVIRONMENT
 - 3.1.- HARDWARE – 10 MINS
 - Cables, transceivers, license (CANcase, CANcard)
 - 3.2.- SNIFFING – 160 MINS
 - 3.2.1.- CREATE A NEW PROJECT – 20 MINS
 - DDBB, channels, baud rate (low&high).
 - 3.2.2.- CANOE WINDOWS – 140 MINS
 - Explanation about buttons, menus and options for different CANoe windows.
 - 3.3.- CREATE A SIMULATION: DESIGN AND DEVELOPMENT – 120 MINS
 - 3.3.1.- CANDB EDITOR – 30 MINS
 - Define Network nodes, messages and signals in order to create a DB.
 - 3.3.2.- PROGRAMMING: CAPL – 60 MINS
 - CAPL Nodes management
 - CAPL browser
 - Messages
 - Events management
 - DLL: library of routines
 - 3.3.3.- MODELLING- 30 MINS
 - Environment Variables
 - Panel Editor
 - 3.4.- FUNCTION BLOCKS – 60 MINS
 - How to define them and behaviour.
 - 3.4.1.- GENERATOR BLOCK – 20 MINS
 - 3.4.2.- INTERACTIVE GENERATOR BLOCK. – 20 MINS
 - 3.4.3.- REPLAY BLOCK – 20 MINS
- 4.- OPTICAL RINGS AND TOOLS
 - 4.1.- D2B OPTOLYZER – 30 MINS
 - Equipment needed
 - Optolyzer: Mode, Setup, Recorder and Viewer
 - 4.2.- MOST OPTOLYZER – 30 MINS
 - Equipment required
 - Optolyzer: initialization, configuration, viewer, recorder, filters and masks



PRACTICE (40 HOURS) – Average of 5h per practice

0. Physical layer on the CAN bus

Analyze CAN frames with the help of an oscilloscope, checking issues such as voltages and bit periods in different CAN buses, and the way in which bit stuffing works.

Bench: BR203

Buses: CAN B, CAND

Devices: CGW, TeleAid

1. CAN analysis: IGN signals, TeleAid Info-Call and Volume control

Trace CAN messages with the CANoe tool analyzing the traces and comparing them with the associated K-Matrix. Analyze the messages sent when the ignition of the car is turned on/off in order to understand how the vehicle bus wakes up. Identify the CAN messages transmitted when the volume control is changed or when the hang button is pressed during a TeleAid service call.

Bench: BR211

Buses: CAN B

Devices: EIS, HU, CP

2. CAN analysis: Airbag signals

Trace airbag CAN messages with CANoe tool in BR211. Analyze the messages sent by the airbag sensor when a crash happens simulating the crash by shaking the airbag sensor.

Bench: BR211

Buses: CAN B

Devices: CP, Airbag sensor

3. Real Car Trace

Analyze a standard CAN trace previously measured in a vehicle at DCAG in order to identify the messages and signals that are exchanged in a real car. The different signals should be identified by analyzing manually the traces.

Bench: None

Buses: CAN D

Devices: None

4. Wake up by trunk button

Modify or create a CANoe project by adding an Interactive Generator Block. It should send the “trunk button pressed” signal in order to wake up the CP as a RDU scenario.

Benches: BR211

Buses: CAN B

Devices: CP

5. TeleAid MMI warnings (IC/HU). CAPL Programming

Connect the CANoe tool to a Suitcase Tester. Program in CAPL (CANoe Access Programming Language) and modify an already programmed CAPL application by adding new panels or tracing event and displaying them in the different CANoe windows.

Benches: Text Box

Buses: CAN D

Devices: Test Box, LCT

6. D2B Optical Bus Analyzer

Trace the D2B bus with the Optolyzer tool to reproduce and analyze the System Start-Up and Initialization Procedure, the normal mode and the shutdown of the optical D2B ring.

Bench: BR220

Buses: D2B

Devices: HU, CD-Changer, Sound amplifier, ECall2



7. MOST Optical Bus analyzer. HU-Telephony MMI

Trace the MOST bus with the Optolyzer4MOST and analyze the system initialization and the communication between the HU and the telephone during different events.

Benches: BR203

Buses: MOST

Devices: HU, Telephony

MATERIAL

a) BENCH BR211 CP (E-CLASS)

This Bench includes

Central Gateway	Instrument Cluster 211	Speech Dialog System	Mobil Telephone and cradle
Airbag Sensor	Audio Gateway (basic)	Electric Ignition System	Head Unit Comand Becker
Communication Platform TeleAid			

b) BENCH BR211 CP RETROFIT (E-CLASS)

This Bench includes

Central Gateway	Instrument Cluster 211	Speech Dialog System	Mobil Telephone and cradle
Airbag Sensor	Audio Gateway Sound	Electric Ignition System	Head Unit Comand Becker
Communication Platform TeleAid			

c) BENCH BR220 ECALL-2 (S-CLASS)

This Bench includes

Head Unit Comand Becker	Instrument Cluster	GPS Antenna	Audio Gateway
Airbag Sensor	CD Changer	ECall2	

d) BENCH BR203 LCT (C-CLASS)

This Bench includes

Central Gateway	Instrument Cluster 203	SDARS	Mobil Telephone and cradle
Airbag Sensor	Audio Gateway Sound	Electric Ignition System	Head Unit 203
Universal Mobile Interface		Low Cost TeleAid	



- e) TEXT BOX+ LCT + AIRBAG
- f) CANOE AND CANCASEXL
- g) D2B SOFTWARE AND ANALYZER
- h) MOST SOFTWARE AND ANALYZER

ADDITIONAL BIBLIOGRAPHY /ANNEXES

- *CANoe User Manual*
- *Programming With CAPL*
- *Transport Protocol Telegram and Warning Types*
- *D2B Optical Basic Protocols*
- *MOST Function Catalog*
- *MOST Specification*